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### **On the COMS Data Product Timeliness**

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**KARI** 



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## Introduction (1)

COMS System Operational Architecture



# Introduction (2)

COMS INR (Image Navigation and Registration)

A noble approach based on

"A Posteriori" Least Square processing algorithm

- high dependence on the 'landmark measurements'
- executed in 'batch' type data processing

### Introduction (3)

#### COMS INR, overall architecture



## Introduction (4)

- `Timeliness'
  - A dictionary definition :

"the state of happening or appearing at the right or an opportune time"

- Interchangeably used in almost the same meaning/way as the product 'latency' or the processing time delay
- A key parameter for a meteorological sensing system, mainly because of the urgency associated with the management of severe weather events, among others

# Status (1)

### Current Operational Status

All within spec., with very good Nav. & Reg. performances, but in terms of the timeliness ...

 \* Origin of the Issue
 Ref: (COMS System Req. Spec.)
 3.7 Timeliness and Coverage of Meteorological Data Delivery (SR - 128/)
 \* For the meteorological mission, the HRIT and LRIT data shall be delivered to end users within 15 minutes

after the end of image acquisition."

## Status (2)

#### Current Operational Status

ENH													
Raw d	ata reception			730s		Requirement : <15 mn							
Level 0			3	770s	i								
Level 1A				720s	!	i l							
INRSN	Ŵ		1	1140s									
THEE	L/HRIT Generation		1 1		!		480s	1 1					
LHGS	L/HRIT Dissemination		i ¦			1 1			180s				
Input time delay		100s	50s I	620s	10	i	680s		1				
Output time delay			33. 		40s	50s	430s	40s	3 <mark>4</mark> 0s				

FD													
Raw data reception			1610s						Requirement : <15 mn				
Level 0		1620s											
Level 1A				1530s				i.	1				
INRSM				I	2070s				I				
LUCS	L/HRIT Generation				I			i i	1050s	1 1			
LHGS	L/HRIT Dissemination			i				1	1020s				
Input time delay			120s	50s	1 920s	400s	1		·				
Output time delay							1	0s30s	490s	100s	270s		

### Actions for Resolutions

• Efforts for Resolution/Improvement

(A) Approach on the Hardware

- Improvement on INR processing machines, using a single multi-core system
- (B) Approach on the Existing Algorithm
  - Enhancement of the existing algorithm efficiency and the overall integrity of the operational software
- (C) Approach with a New Algorithm
  - Partial replacement of the "a posteriori" least square algorithm with a real-time Kalman filter algorithm

## Progress and Expectations (1)

#### • Some Key Results (in approach (C))



### **Progress and Expectations (2)**

Expected Implementation and Performances

#### (I) In Approaches (A) and (B)

ENH													
Raw data reception					730s	Requirement : <15 mn							
Level 0			770s										
Level 1A				l	720s	1	1						
INRSM				1	1140s		i						
LICC	L/HRIT Generation			1		1		480s					
LHGS	L/HRIT Dissemination					 	1			18	30s		
Input time delay			100s	50s	620s		I	680s		1			
Output time delay						40s	50s	430s	40s	340s			

FD														
Raw data reception			1610s						Requirement : <15 mn					
Level 0			1620s											
Level 1A			1530s											
INRSM	INRSM		2070s					1						
LICO	L/HRIT Generation			I	1			1050s						
LHGS	L/HRIT Dissemination			1	i I	1		I	1020s					
Input ti	me delay		120s	50s	920s	i 400s	 	-						
Output time delay							10s	0s	490s	100s	270s			

### **Progress and Expectations (3)**

Expected Implementation and Performances

### (II) In Approaches (C)

ENH													
Raw data reception					730s	Requirement : <15 mn							
Level 0					770s								
Level 1A				l	720s								
INRSM				1	1140s								
LICO	L/HRIT Generation			I			1	1 480s					
LHGS	L/HRIT Dissemination			1	1	+				180s			
Input time delay			100s	¦ 50s	620s		I	680s		1			
Output time delay						40s	50s	430s	40s	340s			

FD													
Raw data reception			1610s						Requirement : <15 mn				
Level 0			1620s										
Level 1A					1530s								
INRSM					2070s				.1				
LUCS	L/HRIT Generation			I	4				1050s				
LHGS	L/HRIT Dissemination							i !	1020s				
Input ti	Input time delay		120s	50s	920	)s	i 400s		-				
Output time delay								10s30	490s	100s	270s		

# Conclusion and Discussions (1)

- With the completed implementation of the current efforts tar geted in 2014, it is anticipated that COMS data product timeli ness will be in the comparable range with that of MTSAT2 an d other similar meteorological satellites.
- It is anticipated that the value of COMS data products then will be accordingly enhanced for the benefit of user communi ty in this region, with the comparison and in conjunction wit h other similar data products.
- The lessons-learned herein exemplify and signify that the us er-developer interface/interaction is critical, and especially in the early program definition phase. It can impact the whole course of satellite development, ground/in-orbit validation an d the final use and application of the satellite end products, i n terms of cost, schedule and final utility of the data.

### **Conclusion and Discussions (2)**

- Close dialogue and efficient discussion should be in place betw een user and developer to minimize or eliminate in advance thi s nature of negative impact.
- System engineering in the large scale should be able to compensate this impact due to the potential mis-specification in the program definition phase, by interactive and flexible adjustment, modification and/or reconfiguration of both specification and development concept, through the entire course of satellite development and in the final application.
- It is anticipated from here on that more active dialogue and inf ormation share in the user community in this region will help t o prevent the recurrence of similar issues of this nature in adv ance and lessen the burden of resolving them.

# Conclusion and Discussions (3)

 "In our increasingly inter-dependent world, winning requires more than just delivering on your own promises. It means en suring that a host of partners – some visible, some hidden – deliver on their promises, too."

- Ron Adner, 'The Wide Lens'